



# **Electricity and Magnetism II**

**Lecture No.(3)- Semester 2**

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# Sources of Magnetic Fields

## 9.1 Biot-Savart Law

Currents which arise due to the motion of charges are the source of magnetic fields. When charges move in a conducting wire and produce a current  $I$ , the magnetic field at any point  $P$  due to the current can be calculated by adding up the magnetic field contributions,  $d\vec{B}$ , from small segments of the wire  $d\vec{s}$ , (Figure 9.1.1).

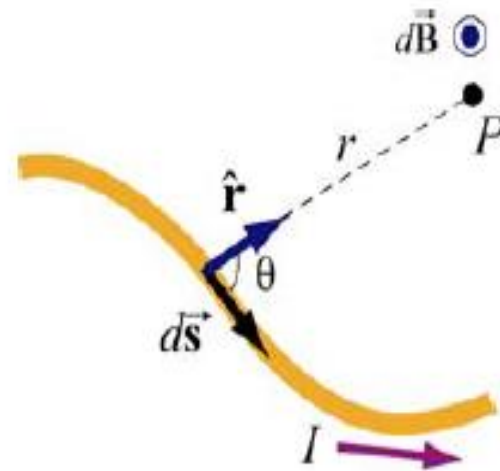


Figure 9.1.1 Magnetic field  $d\vec{B}$  at point  $P$  due to a current-carrying element  $I d\vec{s}$ .

These segments can be thought of as a vector quantity having a magnitude of the length of the segment and pointing in the direction of the current flow. The infinitesimal current source can then be written as  $I d\vec{s}$ .

Let  $r$  denote as the distance from the current source to the field point  $P$ , and  $\hat{\mathbf{r}}$  the corresponding unit vector. The Biot-Savart law gives an expression for the magnetic field contribution,  $d\vec{\mathbf{B}}$ , from the current source,  $I d\vec{s}$ ,

$$\boxed{d\vec{\mathbf{B}} = \frac{\mu_0}{4\pi} \frac{I d\vec{s} \times \hat{\mathbf{r}}}{r^2}} \quad (9.1.1)$$

where  $\mu_0$  is a constant called the *permeability of free space*:

$$\mu_0 = 4\pi \times 10^{-7} \text{ T} \cdot \text{m/A} \quad (9.1.2)$$

Notice that the expression is remarkably similar to the Coulomb's law for the electric field due to a charge element  $dq$ :

$$d\vec{\mathbf{E}} = \frac{1}{4\pi\epsilon_0} \frac{dq}{r^2} \hat{\mathbf{r}} \quad (9.1.3)$$

Adding up these contributions to find the magnetic field at the point  $P$  requires integrating over the current source,

$$\vec{\mathbf{B}} = \int_{\text{wire}} d\vec{\mathbf{B}} = \frac{\mu_0 I}{4\pi} \int_{\text{wire}} \frac{d\vec{\mathbf{s}} \times \hat{\mathbf{r}}}{r^2} \quad (9.1.4)$$

The integral is a vector integral, which means that the expression for  $\vec{\mathbf{B}}$  is really three integrals, one for each component of  $\vec{\mathbf{B}}$ . The vector nature of this integral appears in the cross product  $I d\vec{\mathbf{s}} \times \hat{\mathbf{r}}$ . Understanding how to evaluate this cross product and then perform the integral will be the key to learning how to use the Biot-Savart law.

## Example 9.1: Magnetic Field due to a Finite Straight Wire

A thin, straight wire carrying a current  $I$  is placed along the  $x$ -axis, as shown in Figure 9.1.3. Evaluate the magnetic field at point  $P$ . Note that we have assumed that the leads to the ends of the wire make canceling contributions to the net magnetic field at the point  $P$ .

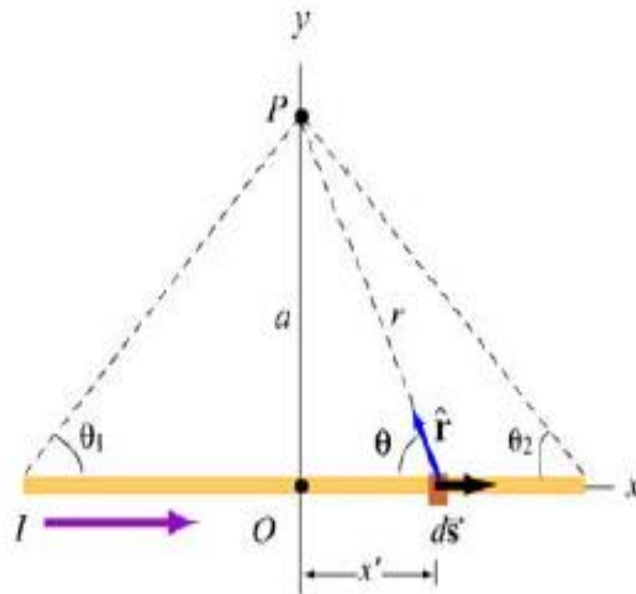


Figure 9.1.3 A thin straight wire carrying a current  $I$ .

## Solution:

This is a typical example involving the use of the Biot-Savart law. We solve the problem using the methodology summarized in Section 9.10.

(1) Source point (coordinates denoted with a prime)

Consider a differential element  $d\vec{s} = dx'\hat{\mathbf{i}}$  carrying current  $I$  in the  $x$ -direction. The location of this source is represented by  $\vec{\mathbf{r}}' = x'\hat{\mathbf{i}}$ .

(2) Field point (coordinates denoted with a subscript “ $P$ ”)

Since the field point  $P$  is located at  $(x, y) = (0, a)$ , the position vector describing  $P$  is  $\vec{\mathbf{r}}_P = a\hat{\mathbf{j}}$ .

### (3) Relative position vector

The vector  $\vec{\mathbf{r}} = \vec{\mathbf{r}}_P - \vec{\mathbf{r}}'$  is a “relative” position vector which points from the source point to the field point. In this case,  $\vec{\mathbf{r}} = a\hat{\mathbf{j}} - x'\hat{\mathbf{i}}$ , and the magnitude  $r = |\vec{\mathbf{r}}| = \sqrt{a^2 + x'^2}$  is the distance from between the source and  $P$ . The corresponding unit vector is given by

$$\hat{\mathbf{r}} = \frac{\vec{\mathbf{r}}}{r} = \frac{a\hat{\mathbf{j}} - x'\hat{\mathbf{i}}}{\sqrt{a^2 + x'^2}} = \sin\theta\hat{\mathbf{j}} - \cos\theta\hat{\mathbf{i}}$$

### (4) The cross product $d\vec{\mathbf{s}} \times \hat{\mathbf{r}}$

The cross product is given by

$$d\vec{\mathbf{s}} \times \hat{\mathbf{r}} = (dx'\hat{\mathbf{i}}) \times (-\cos\theta\hat{\mathbf{i}} + \sin\theta\hat{\mathbf{j}}) = (dx'\sin\theta)\hat{\mathbf{k}}$$



(5) Write down the contribution to the magnetic field due to  $I d\vec{s}$

The expression is

$$d\vec{\mathbf{B}} = \frac{\mu_0 I}{4\pi} \frac{d\vec{\mathbf{s}} \times \hat{\mathbf{r}}}{r^2} = \frac{\mu_0 I}{4\pi} \frac{dx \sin \theta}{r^2} \hat{\mathbf{k}}$$

which shows that the magnetic field at  $P$  will point in the  $+\hat{\mathbf{k}}$  direction, or out of the page.

(6) Simplify and carry out the integration

The variables  $\theta$ ,  $x$  and  $r$  are not independent of each other. In order to complete the integration, let us rewrite the variables  $x$  and  $r$  in terms of  $\theta$ . From Figure 9.1.3, we have

$$\begin{cases} r = a / \sin \theta = a \csc \theta \\ x = a \cot \theta \Rightarrow dx = -a \csc^2 \theta d\theta \end{cases}$$

Upon substituting the above expressions, the differential contribution to the magnetic field is obtained as

$$dB = \frac{\mu_0 I}{4\pi} \frac{(-a \csc^2 \theta d\theta) \sin \theta}{(a \csc \theta)^2} = -\frac{\mu_0 I}{4\pi a} \sin \theta d\theta$$

Integrating over all angles subtended from  $-\theta_1$  to  $\theta_2$  (a negative sign is needed for  $\theta_1$  in order to take into consideration the portion of the length extended in the negative  $x$  axis from the origin), we obtain

$$B = -\frac{\mu_0 I}{4\pi a} \int_{-\theta_1}^{\theta_2} \sin \theta \, d\theta = \frac{\mu_0 I}{4\pi a} (\cos \theta_2 + \cos \theta_1) \quad (9.1.5)$$

The first term involving  $\theta_2$  accounts for the contribution from the portion along the  $+x$  axis, while the second term involving  $\theta_1$  contains the contribution from the portion along the  $-x$  axis. The two terms add!

Let's examine the following cases:

(i) In the symmetric case where  $\theta_2 = -\theta_1$ , the field point  $P$  is located along the perpendicular bisector. If the length of the rod is  $2L$ , then  $\cos \theta_1 = L / \sqrt{L^2 + a^2}$  and the magnetic field is

$$B = \frac{\mu_0 I}{2\pi a} \cos \theta_1 = \frac{\mu_0 I}{2\pi a} \frac{L}{\sqrt{L^2 + a^2}} \quad (9.1.6)$$

(ii) The infinite length limit  $L \rightarrow \infty$

This limit is obtained by choosing  $(\theta_1, \theta_2) = (0, 0)$ . The magnetic field at a distance  $a$  away becomes

$$\boxed{B = \frac{\mu_0 I}{2\pi a}} \quad (9.1.7)$$

## Example 9.2: Magnetic Field due to a Circular Current Loop

A circular loop of radius  $R$  in the  $xy$  plane carries a steady current  $I$ , as shown in Figure 9.1.6.

(a) What is the magnetic field at a point  $P$  on the axis of the loop, at a distance  $z$  from the center?

(b) If we place a magnetic dipole  $\vec{\mu} = \mu_z \hat{\mathbf{k}}$  at  $P$ , find the magnetic force experienced by the dipole. Is the force attractive or repulsive? What happens if the direction of the dipole is reversed, i.e.,  $\vec{\mu} = -\mu_z \hat{\mathbf{k}}$

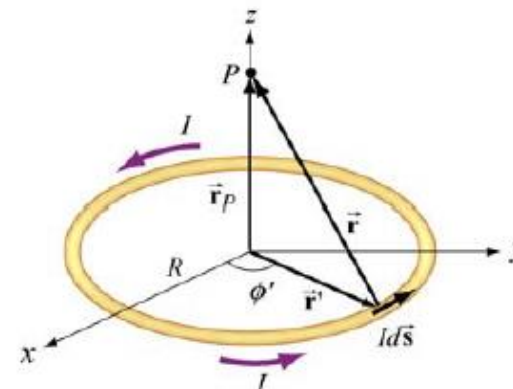


Figure 9.1.6 Magnetic field due to a circular loop carrying a steady current.

## Solution:

(a) This is another example that involves the application of the Biot-Savart law. Again let's find the magnetic field by applying the same methodology used in Example 9.1.

(1) Source point

In Cartesian coordinates, the differential current element located at  $\vec{r}' = R(\cos \phi' \hat{i} + \sin \phi' \hat{j})$  can be written as  $I d\vec{s} = I(d\vec{r}' / d\phi') d\phi' = IR d\phi' (-\sin \phi' \hat{i} + \cos \phi' \hat{j})$ .

(2) Field point

Since the field point  $P$  is on the axis of the loop at a distance  $z$  from the center, its position vector is given by  $\vec{r}_p = z\hat{k}$ .

(3) Relative position vector  $\vec{\mathbf{r}} = \vec{\mathbf{r}}_P - \vec{\mathbf{r}}'$

The relative position vector is given by

$$\vec{\mathbf{r}} = \vec{\mathbf{r}}_P - \vec{\mathbf{r}}' = -R \cos \phi' \hat{\mathbf{i}} - R \sin \phi' \hat{\mathbf{j}} + z \hat{\mathbf{k}} \quad (9.1.8)$$

and its magnitude

$$r = |\vec{\mathbf{r}}| = \sqrt{(-R \cos \phi')^2 + (-R \sin \phi')^2 + z^2} = \sqrt{R^2 + z^2} \quad (9.1.9)$$

is the distance between the differential current element and  $P$ . Thus, the corresponding unit vector from  $Id \vec{\mathbf{s}}$  to  $P$  can be written as

$$\hat{\mathbf{r}} = \frac{\vec{\mathbf{r}}}{r} = \frac{\vec{\mathbf{r}}_P - \vec{\mathbf{r}}'}{|\vec{\mathbf{r}}_P - \vec{\mathbf{r}}'|}$$

(4) Simplifying the cross product

The cross product  $d\vec{s} \times (\vec{r}_P - \vec{r}')$  can be simplified as

$$\begin{aligned}d\vec{s} \times (\vec{r}_P - \vec{r}') &= R d\phi' (-\sin \phi' \hat{i} + \cos \phi' \hat{j}) \times [-R \cos \phi' \hat{i} - R \sin \phi' \hat{j} + z \hat{k}] \\ &= R d\phi' [z \cos \phi' \hat{i} + z \sin \phi' \hat{j} + R \hat{k}]\end{aligned}\tag{9.1.10}$$

(5) Writing down  $d\vec{B}$

Using the Biot-Savart law, the contribution of the current element to the magnetic field at  $P$  is

$$\begin{aligned}d\vec{B} &= \frac{\mu_0 I}{4\pi} \frac{d\vec{s} \times \hat{r}}{r^2} = \frac{\mu_0 I}{4\pi} \frac{d\vec{s} \times \vec{r}}{r^3} = \frac{\mu_0 I}{4\pi} \frac{d\vec{s} \times (\vec{r}_P - \vec{r}')}{|\vec{r}_P - \vec{r}'|^3} \\ &= \frac{\mu_0 I R}{4\pi} \frac{z \cos \phi' \hat{i} + z \sin \phi' \hat{j} + R \hat{k}}{(R^2 + z^2)^{3/2}} d\phi'\end{aligned}\tag{9.1.11}$$



(6) Carrying out the integration

Using the result obtained above, the magnetic field at  $P$  is

$$\bar{\mathbf{B}} = \frac{\mu_0 IR}{4\pi} \int_0^{2\pi} \frac{z \cos \phi' \hat{\mathbf{i}} + z \sin \phi' \hat{\mathbf{j}} + R \hat{\mathbf{k}}}{(R^2 + z^2)^{3/2}} d\phi' \quad (9.1.12)$$

The  $x$  and the  $y$  components of  $\bar{\mathbf{B}}$  can be readily shown to be zero:

$$B_x = \frac{\mu_0 IRz}{4\pi(R^2 + z^2)^{3/2}} \int_0^{2\pi} \cos \phi' d\phi' = \frac{\mu_0 IRz}{4\pi(R^2 + z^2)^{3/2}} \sin \phi' \Big|_0^{2\pi} = 0 \quad (9.1.13)$$

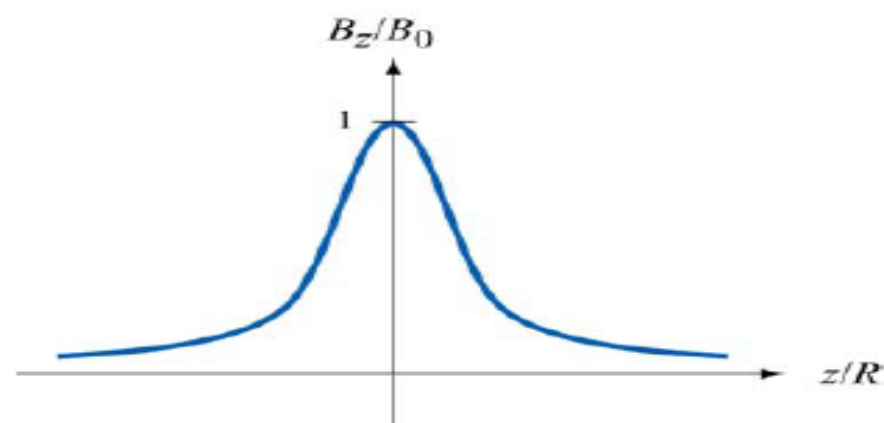
$$B_y = \frac{\mu_0 IRz}{4\pi(R^2 + z^2)^{3/2}} \int_0^{2\pi} \sin \phi' d\phi' = -\frac{\mu_0 IRz}{4\pi(R^2 + z^2)^{3/2}} \cos \phi' \Big|_0^{2\pi} = 0 \quad (9.1.14)$$

On the other hand, the  $z$  component is

$$B_z = \frac{\mu_0}{4\pi} \frac{IR^2}{(R^2 + z^2)^{3/2}} \int_0^{2\pi} d\phi' = \frac{\mu_0}{4\pi} \frac{2\pi IR^2}{(R^2 + z^2)^{3/2}} = \frac{\mu_0 IR^2}{2(R^2 + z^2)^{3/2}} \quad (9.1.15)$$

Thus, we see that along the symmetric axis,  $B_z$  is the only non-vanishing component of the magnetic field. The conclusion can also be reached by using the symmetry arguments.

The behavior of  $B_z / B_0$  where  $B_0 = \mu_0 I / 2R$  is the magnetic field strength at  $z = 0$ , as a function of  $z / R$  is shown in Figure 9.1.7:



**Figure 9.1.7** The ratio of the magnetic field,  $B_z / B_0$ , as a function of  $z / R$

(b) If we place a magnetic dipole  $\vec{\mu} = \mu_z \hat{\mathbf{k}}$  at the point  $P$ , as discussed in Chapter 8, due to the non-uniformity of the magnetic field, the dipole will experience a force given by

$$\vec{\mathbf{F}}_B = \nabla(\vec{\mu} \cdot \vec{\mathbf{B}}) = \nabla(\mu_z B_z) = \mu_z \left( \frac{dB_z}{dz} \right) \hat{\mathbf{k}} \quad (9.1.16)$$

Upon differentiating Eq. (9.1.15) and substituting into Eq. (9.1.16), we obtain

$$\vec{\mathbf{F}}_B = -\frac{3\mu_z \mu_0 I R^2 z}{2(R^2 + z^2)^{5/2}} \hat{\mathbf{k}} \quad (9.1.17)$$

Thus, the dipole is attracted toward the current-carrying ring. On the other hand, if the direction of the dipole is reversed,  $\vec{\mu} = -\mu_z \hat{\mathbf{k}}$ , the resulting force will be repulsive.

